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Linear and Nonlinear

separate parts Part I is a self-contained introduction to linear programming, a key component of optimization theory The presentation in this part is fairly conventional, covering the main elements of the underlying theory of linear programming, many of the most effective numerical algorithms, and many of its important special applications

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Nonlinear Programming: Theory and Algorithms Third Edition Mokhtar S Bazaraa Department of Industrial and Systems Engineering Georgia Institute of Technology Atlanta, GA Hanif D Sherali Department of Industrial and Systems Engineering Virginia Polytechnic Institute and State University Blacksburg, VA C M Shetty

Optimization (SF1811/SF1831/SF1841)

111 Linear programming If the objective function is a linear function and the feasible set is given by a bunch of linear inequalities, then the corresponding optimization problem (11) is called linear programming Thus the general linear programming problem has the following form: $\hat{\text{minimize}} c^T x$, subject to $Ax \geq b$,

Linear and Nonlinear Programming

ming, a powerful generalization of Linear Programming While the constraint set in a normal linear program is defined by a finite number of linear inequalities of finite-dimensional vector variables, the constraint set in conic linear programming may be defined, for example, as a linear

combination of symmetric positive semi-

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